

ELECTRIC MOTOR ACTUATOR FOR A MOTOR VEHICLE LOCK

Background of the Invention

Field of the Invention

[0001] The present invention pertains generally to an electric motor actuator for a motor vehicle lock for a side door lock, rear door lock, hood lock or the like. More specifically, the present invention is directed to an electric motor actuator for a motor vehicle lock and includes a reversible drive motor and an actuator drive which can be rotary driven by the drive motor. The electric motor actuator further includes an operating lever which is dynamically coupled to the actuator drive for switching the lock into an "unlocked" and "locked" operating state, an antitheft lever which is spring-loaded with a pretensioning spring and which is dynamically coupled to the actuator drive for holding the operating lever in the "locked" operating state. An emergency actuating element is used for manually engaging an antitheft lever into an "antitheft off" operating state to overcome a catch element on the actuator drive. The antitheft lever can be switched out of the "antitheft off" operating state into an "antitheft" operating state through a pretensioning spring on the antitheft lever such that the antitheft lever is held in the "antitheft off" operating state by a control crank on the actuator drive, and is held in the "unlocked" operating state by the operating lever.

Description of the Related Art

[0002] German Patent DE 44 33 994 C1 discloses a conventional electric motor actuator for a motor vehicle lock including an actuator element comprising an actuator disk which is

driven clockwise and counterclockwise by an electric drive motor, and therefore can be reversibly driven. Other prior art devices of the type mentioned above are disclosed in German Patent DE 33 19 354 C2, U.S. Patent No. 5,409,277, and Published German Application DE 198 27 751 A1.

[0003] These prior art devices, however, fail to disclose a more detailed configuration of a combination including a drive motor and an actuator disk. An electric motor actuator having an actuator disk as the actuator element has proven to be compact and reliable. In one such motor vehicle lock, an actuator disk is regularly used with an actuating lever system and a locking lever system. Generally, the actuating lever system has an outer actuating lever and an inner actuating lever whereby the outer actuating lever is connected to an outside door handle, while the inner actuating lever is connected to an inner door handle. The locking lever system generally has at least one inner locking lever that is either made separately, for example, leading to an inside locking button, or can also be integrated with the inner actuating lever. On the front side doors of a motor vehicle and on the rear door of a station wagon there is also an outer locking lever which is connected to a lock cylinder and/or a remote control means.

[0004] The use of a "locked-antitheft" operating state means that the motor vehicle lock cannot be opened by undue application of force to the inner locking lever and/or the inner actuating lever. This unallowable application of force is possible after breaking a window, but should remain ineffective in the "locked-antitheft" operating state. The locking lever system of the motor vehicle lock is switched back and forth by means of the electric motor actuator between the operating states "unlocked", "locked", and "locked-antitheft". The operating lever of the actuator can be manually switched back and forth between the "unlocked" and "locked" operating states. If, however, the actuator is in the "locked-antitheft" operating state, the operating lever is blocked in the "locked" operating state by way of the antitheft lever. If the electric drive motor fails in this operating position, actuation must be produced by way of a mechanical emergency actuating element which engages the antitheft

[0006] In such electric motor actuators, manual unlocking when the central interlock drive fails can be accomplished easily, reliably and promptly. The construction of the antitheft lever necessary for this purpose with pretensioning springs and a raisable catch is, however, relatively complex in terms of mechanical construction. In addition, when the spring of the pretensioning spring for the antitheft lever breaks, emergency mechanical actuation is no longer possible. The arrangement of the actuator disk, the operating lever and the raisable catch in the above-explained electric motor actuator is such that the catch in the "antitheft" operating state must accommodate very high forces under certain circumstances. This high application of force to the catch can only be structurally accomplished with difficulty. Only with very high quality materials which are then correspondingly expensive can this be done. Kinematically, this arrangement has a defect in that the directions of rotation of the actuator disk are not unequivocal for throwing over the operating lever.

[0007] Based upon the design having a catch and pretensioning spring on the antitheft lever, it is necessary that the operating lever is thrown over once clockwise, another time counterclockwise into the same operating state, therefore, into a "locked" or "unlocked"

operating state. Which direction of rotation is actually necessary is then determined by the respective position of the catch. Therefore a very intelligent, efficient electronic control is necessary; this again results in major costs.

Summary of the Invention

[0008] Accordingly, it is an object of the present invention to overcome the aforementioned disadvantages in improving the design of the conventional electric motor actuator of the initially mentioned type with consideration of the requirements for emergency mechanical actuation.

[0009] This object is achieved in an electric motor actuator for a motor vehicle lock having an antitheft lever that is automatically controlled by an actuator drive, and thus not in conjunction with an operating lever. Control of the antitheft lever takes place such that the antitheft lever is pretensioned by means of a pretensioning spring or the like in the direction of an "antitheft" operating state, and therefore, can be switched from an "antitheft off" operating state into an "antitheft" operating state. If the pretensioning spring breaks, the antitheft lever remains either in the "antitheft off" operating state or can be manually/mechanically switched into an operating state by means of an emergency actuation mechanism. Moreover, an additional catch is not employed since the antitheft lever can be held by a control crank on the actuator drive or disk in the "antitheft off" operating state.

[0010] Other advantages are provided due to the elimination of an addition catch, and thereby an additional spring mechanism. In addition, control of the electric motor actuator can be made simple due to the overall construction causes the actuator disk to unambiguously activate the operating lever. Consequently, a single direction of rotation of the actuator disk is always assigned to the displacement of the operating lever into the same operating state. In accordance with an aspect of the present invention, it is, however, advantageous that the desired manner of operation of the actuator be preserved and nevertheless the antitheft function has been integrated into the actuator itself.

[0011] Another advantage of the electric motor actuator in accordance to the present invention is also its compact structure which can be especially facilitated by the actuator disk or the like being made in three planes, specifically a middle plane for coupling the actuator disk to the electric drive motor, a lower plane for coupling the actuator disk to the operating lever, and an upper plane for coupling the actuator disk to the antitheft lever. The terms "lower" and "upper" are interchangeable and in this case according to the preferred teaching are defined such that "lower" means the position nearest the bottom of the housing and "upper" means the position farthest from the housing bottom.

[0012] The present invention will be better understood by those skilled in the art and the above objects will become more apparent in the following detailed description of the preferred embodiment of the invention.

Detailed Description of the Drawings

[0013] Fig. 1 shows a preferred embodiment of an electric motor actuator for a motor vehicle lock in the "lower" plane and "unlocked" operating state;

[0014] Fig. 2 shows the electric motor actuator of Figure 1 in the "upper" plane and "unlocked" operating state;

[0015] Figs. 3 shows an electric motor actuator for a motor vehicle lock in the "lower" plane and "locked" operating state

[0016] Fig. 4 shows the electric motor actuator in the "upper" plane and "locked" operating state;

[0017] Figure 5 shows the actuator of Figure 2 in the "locked-antitheft" operating state; and

[0018] Figure 6 shows the actuator of Figure 2 in the "locked-antitheft" operating state, the antitheft lever moved mechanically-manually into the "antitheft-off" operating state.

Detailed Description of the Preferred Embodiment

[0019] Referring now to the drawings, Figs. 1 and 2 show in conjunction the basic structure of the preferred embodiment of the electric motor actuator for a motor vehicle lock constructed for operation in "unlocked", "locked" and "locked-antitheft" operating states. Accordingly, the actuating lever system of the motor vehicle lock can be switched into these operating states by means of the electric motor actuator as well as mechanically/manually, and especially by means of an emergency actuation function.

[0020] As illustrated in Fig. 1 and 2, an electric motor actuator for a motor vehicle lock including a housing 1 which is opened on one side. The housing 1 first accommodates a reversible drive motor 2 and an actuator disk 4 which can be rotationally driven in this embodiment by the drive motor 2 via a spindle 3. Preferably, the actuator element is a rotationally drivable actuator disk 4, however, a linearly moved actuator element would also be conceivable. The interaction of the actuator disk 4 with the locking lever system is important. An operating lever 5 is dynamically coupled to the actuator disk 4 for switching the lock mechanism, therefore the locking lever system, into a "unlocked" and "locked" operating state. The operating lever 5 is normally loaded with a tilt spring or the like (not shown) so that it always assumes a positively defined position.

[0021] As illustrated in Fig. 1, the operating lever 5 is in the "unlocked" operating state with one side adjoining a buffer 6. The operating lever 5, at least in the end position of the actuator disk 4, can be switched manually back and forth between the "unlocked" and "locked" operating states so that, in cases when the electric motor drive fails, manual unlocking and locking of the motor vehicle lock are possible. Fig. 2 shows a pivotally mounted antitheft lever 7 or the like which is dynamically coupled to the actuator disk 4 or the like. The antitheft lever 7 is loaded by a pretensioning spring 7a and is shown in Fig. 2 in the "antitheft off" operating state because, there, the actuator is in the "unlocked" operating state overall. The direction of action of the pretensioning spring 7a is shown by the curved arrow.

[0022] Figs. 3 and 4 show the device in the "locked" operating state. Fig. 5 shows the "antitheft" operating state of the antitheft lever 7, whereby the antitheft lever 7 holds the operating lever 5, which is in the "locked" operating state, in its "locked" operating state. On the antitheft lever 7 shown in Figs. 2, 4 and 5, there is an actuating projection 8 which can be engaged by a mechanical emergency actuating element, especially a key-actuated outer locking lever of the locking lever system, when the motor vehicle lock is assembled. (direction of the arrow in Figure 5). By way of the emergency actuation element, the antitheft lever 7 can be moved into the "antitheft off" operating state mechanically/manually as the catch 9 or the like is overcome when the actuator disk 4 or the like continues unchanged in the "locked-antitheft" operating state (see Fig. 6).

[0023] In spite of integration of an antitheft feature, the actuator in accordance to the present invention can ensure unambiguous assignment of the direction of rotation of the actuator disk 4 or the like to a "unlocked" or "locked" operating state. In this way, control of the electric motor actuator is simple because changing assignments need not be considered by electronics or circuitry. Accordingly, for the actuator in accordance with the invention, there are many fewer switches and sensors than in the prior art which forms the starting point.

[0024] It is important that the antitheft lever 7 be switched by means of the pretensioning springs 7a or the like from the operating state "antitheft off" (Figs. 2 and 4) into the "antitheft" operating state (Fig. 5). This means that the antitheft lever 7 is pretensioned from the position shown in Fig. 2 by the pretensioning spring 7a with respect to rotation clockwise around a bearing axis 10. Figs. 2 and 4 further show that the antitheft lever 7 is held by a control crank 11 on the actuator disk 4 or the like in the "antitheft off" operating state. Moreover, the antitheft lever 7 is also held in the "antitheft off" operating state by the operating lever 5 which is in the "unlocked" operating state. Figs. 1 and 2 show that a corresponding projection 12 on the operating lever 5 in the position of the operating lever 5 prevents the antitheft lever 7 from turning clockwise under spring force from the position shown in Figure 2. Consequently, if the operating lever 5 is in the "unlocked" operating state,

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Variable	Mean	SD	Min	Max
Age	34.5	10.2	21	55
Gender	0.5	0.5	0	1
Marital status	0.6	0.5	0	1
Education	12.5	1.5	9	16
Income	15.2	5.8	5	35
Occupation	1.2	0.8	0	2
Health status	1.8	0.5	1	3
Stress level	2.5	0.8	1	4
Life satisfaction	3.2	0.6	2	4
Resilience	2.8	0.7	1	4
Optimism	3.5	0.5	2	4
Gratitude	3.8	0.4	2	4
Forgiveness	3.6	0.5	2	4
Empathy	3.4	0.6	2	4
Compassion	3.3	0.5	2	4
Kindness	3.7	0.4	2	4
Generosity	3.9	0.3	2	4
Patience	3.6	0.5	2	4
Self-control	3.5	0.4	2	4
Emotional stability	3.4	0.5	2	4
Psychological well-being	3.3	0.4	2	4
Life purpose	3.2	0.5	2	4
Meaning in life	3.1	0.4	2	4
Existential well-being	3.0	0.5	2	4
Transcendental well-being	2.9	0.4	2	4
Overall well-being	2.8	0.5	2	4

Variable	Mean	SD	Min	Max
Age	34.5	10.2	21	55
Gender	0.5	0.5	0	1
Marital status	0.6	0.5	0	1
Education	12.5	1.5	9	16
Income	15.2	5.8	5	35
Occupation	1.2	0.8	0	2
Health status	1.8	0.5	1	3
Stress level	2.5	0.8	1	4
Life satisfaction	3.2	0.6	2	4
Resilience	2.8	0.7	1	4
Optimism	3.5	0.5	2	4
Gratitude	3.8	0.4	2	4
Forgiveness	3.6	0.5	2	4
Empathy	3.4	0.6	2	4
Compassion	3.3	0.5	2	4
Kindness	3.7	0.4	2	4
Generosity	3.9	0.3	2	4
Patience	3.6	0.5	2	4
Self-control	3.5	0.4	2	4
Emotional stability	3.4	0.5	2	4
Psychological well-being	3.3	0.4	2	4
Life purpose	3.2	0.5	2	4
Meaning in life	3.1	0.4	2	4
Existential well-being	3.0	0.5	2	4
Transcendental well-being	2.9	0.4	2	4
Overall well-being	2.8	0.5	2	4

Variable	Mean	SD	Min	Max
Age	34.5	10.2	22	55
Gender	0.5	0.5	0	1
Marital status	0.6	0.5	0	1
Education	12.5	1.5	10	15
Income	1500	500	1000	2500
Health status	0.8	0.2	0	1
Smoking status	0.3	0.5	0	1
Alcohol consumption	0.2	0.4	0	1
Exercise frequency	0.5	0.5	0	1
Stress level	0.7	0.3	0	1
Sleep quality	0.6	0.4	0	1
Work satisfaction	0.5	0.5	0	1
Life satisfaction	0.7	0.3	0	1
Depression score	0.4	0.5	0	1
Anxiety score	0.3	0.4	0	1
Quality of life	0.6	0.4	0	1
Healthcare utilization	0.5	0.5	0	1
Health insurance	0.9	0.1	0	1
Access to healthcare	0.8	0.2	0	1
Healthcare costs	1000	300	500	2000
Healthcare quality	0.7	0.3	0	1
Healthcare accessibility	0.6	0.4	0	1
Healthcare affordability	0.5	0.5	0	1
Healthcare effectiveness	0.8	0.2	0	1
Healthcare safety	0.9	0.1	0	1
Healthcare patient satisfaction	0.7	0.3	0	1
Healthcare provider satisfaction	0.6	0.4	0	1
Healthcare system performance	0.5	0.5	0	1
Healthcare system efficiency	0.4	0.5	0	1
Healthcare system equity	0.3	0.4	0	1
Healthcare system sustainability	0.2	0.4	0	1
Healthcare system innovation	0.1	0.3	0	1
Healthcare system transparency	0.0	0.2	0	1
Healthcare system accountability	0.0	0.1	0	1
Healthcare system integrity	0.0	0.1	0	1
Healthcare system trustworthiness	0.0	0.1	0	1
Healthcare system reliability	0.0	0.1	0	1
Healthcare system predictability	0.0	0.1	0	1
Healthcare system consistency	0.0	0.1	0	1
Healthcare system stability	0.0	0.1	0	1
Healthcare system security	0.0	0.1	0	1
Healthcare system privacy	0.0	0.1	0	1
Healthcare system confidentiality	0.0	0.1	0	1
Healthcare system integrity	0.0	0.1	0	1
Healthcare system trustworthiness	0.0	0.1	0	1
Healthcare system reliability	0.0	0.1	0	1
Healthcare system predictability	0.0	0.1	0	1
Healthcare system consistency	0.0	0.1	0	1
Healthcare system stability	0.0	0.1	0	1
Healthcare system security	0.0	0.1	0	1
Healthcare system privacy	0.0	0.1	0	1
Healthcare system confidentiality	0.0	0.1	0	1
Healthcare system integrity	0.0	0.1	0	1
Healthcare system trustworthiness	0.0	0.1	0	1
Healthcare system reliability	0.0	0.1	0	1
Healthcare system predictability	0.0	0.1	0	1
Healthcare system consistency	0.0	0.1	0	1
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Healthcare system trustworthiness	0.0	0.1	0	1
Healthcare system reliability	0.0	0.1	0	1
Healthcare system predictability	0.0	0.1	0	1
Healthcare system consistency	0.0	0.1	0	1
Healthcare system stability	0.0	0.1	0	1
Healthcare system security	0.0	0.1	0	1
Healthcare system privacy	0.0	0.1	0	1
Healthcare system confidentiality	0.0	0.1	0	1
Healthcare system integrity	0.0	0.1	0	1
Healthcare system trustworthiness	0.0	0.1	0	1
Healthcare system reliability	0.0	0.1	0	1
Healthcare system predictability	0.0			

the material.

[0029] Fig. 2 further illustrates a microswitch 16 which is assigned to the operating lever 5. The microswitch 16 allows starting of the "locked" operating state which is correct in terms of control engineering. After actuating the microswitch 16, the electric drive motor 2 is stopped at a short angular distance by means of plug braking or the like. The microswitch 16 can be actuated via a switch actuating lever 17 to allow suitable force transmission from the operating lever 5 to the microswitch 16. Figs. 1 and 3 show an arrangement and operation of the microswitch 16 with a switch actuating lever 17. In fig. 1, the microswitch 16 is actuated in an "unlocked" operating state, while in Fig. 3 the microswitch 16 is not actuated in a "locked" operating state. The switch actuating lever 17 is moved in the manner shown by the operating lever 5.

[0030] In the representation of the planes, the switch actuating lever 17 lies in the same plane with the operating lever 5. The switch actuating lever 17 is preferably made of plastic because the switch actuating lever 17 is not exposed to overly high force loads. It is not recognizable in the drawings because the configuration of the arrangement is hidden in the lower plane such that the microswitch 16, via the switch actuating lever 17, can be actuated not only by the operating lever 5, but also by an actuating element on the actuator disk 4 or the like, especially via a crank which is located in the shape of a sector in the lower plane on the actuator disk 4. The drawings further illustrate the switch actuating lever 17 on one end has the actual lever arm, while on the other end includes a projecting actuating button which fits into the middle plane.

[0031] With the actuation of the microswitch 16 via the switch actuating lever 17, both by the operating lever 5 and also by the actuator disk 4 or the like, an OR gate or an AND gate can be easily mechanically accomplished. The circuitry particularity which leads to the fact that, in the prior art, the required two microswitches can be replaced by one microswitch with the same control engineering performance shown in the prior art. The actuator disk 4 transfers its motion to the operating lever 5 in the desired manner as follows. The actuator